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# Math 215: Linear Algebra

## PROBLEM SET 9 : DUE NOVEMBER 20

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(20 points) Make sure you are familiar with the Academic Honesty policies for this class, as detailed on the syllabus. All work is due on the given day by 3 PM Grinnell Time, or 7 PM if you LaTeX the assignment.

- (3 points) Show that if  $[T] = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$  then  $T \circ T = R_\pi$  (where  $R_\pi$  is rotation by  $180^\circ$ ).
- (a) (3 points) Let  $A = \begin{pmatrix} \frac{9}{10} & \frac{3}{10} \\ \frac{3}{10} & \frac{1}{10} \end{pmatrix}$ . Compute  $A \cdot A$  and simplify your answer as much as possible. **Show all your work.**  
(b) (3 points) Explain your answer to (a) by geometrically interpreting the matrix  $A$  as a certain linear transformation. (Suggestion: Can you recognize this matrix as one from the families of transformations we discussed?)

- (5 points) One result that is “missing” from Proposition 2.6.6 is the idea that matrix multiplication is commutative. This is stated as:

*For all  $2 \times 2$  matrices  $A$  and  $B$ , we have  $AB = BA$ .*

However, this is a false statement. Using our work from early in the semester, negate this statement and then write a proof of the negation. You should include all your matrix computations in your proof.

- Another “missing” idea from the algebra of matrices is that of *cancellation*. If  $x$ ,  $y$ , and  $z$  are in  $\mathbb{R}$ , and we know that  $xy = xz$ , then we can cancel the  $x$  and conclude that  $y = z$ . This is not true for matrices. Let

$$A = \begin{pmatrix} 3 & -6 \\ -1 & 2 \end{pmatrix}, \quad B = \begin{pmatrix} -1 & 1 \\ 3 & 4 \end{pmatrix}, \quad C = \begin{pmatrix} -3 & -5 \\ 2 & 1 \end{pmatrix}.$$

- (a) (3 points) Compute  $AB$  and  $AC$  and conclude that the products are the same. Show all your work.  
(b) (3 points) Explain what (a) tells us about *cancellation* with matrices.

- (DON'T TURN THIS ONE IN) Let  $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$  be any  $2 \times 2$  matrix. Definition 2.6.3 in the textbook defines  $r \cdot A$  as  $\begin{pmatrix} ra & rb \\ rc & rd \end{pmatrix}$ .

Prove Proposition 2.6.4 which says that if  $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  is a linear transformation and  $r \in \mathbb{R}$ , then  $[r \cdot T] = r \cdot [T]$ .